

Deep Learning Applications for Analysing Concrete Surface Cracks

Sina Aalipour Birgani¹, Sara Shomal Zadeh^{2,*}, Danial Davani Davari³, Amirhossein Ostovar⁴

¹ Master of Mechanical Engineering -Energy Conversion, Sharif University of Technology International Campus Kish Island, Iran

² Department of Civil and Environmental Engineering, Lamar University, USA

Email: sshomalzadeh@lamr.edu

³ University of Southern California, USA

⁴ University of Nevada, Reno, USA

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Abstract

Deep learning is transforming concrete crack analysis into civil engineering, enabling automated, accurate, and scalable detection essential for maintaining infrastructure like bridges, buildings, and roads. Traditional methods, relying on manual inspections or basic image processing, are often time-consuming and prone to errors, especially over large or complex structures. This review explores the application of deep learning models—especially CNNs and advanced architectures like U-Net, Mask R-CNN, and DeepLab—in detecting, segmenting, and quantifying cracks with precision. It also addresses innovations such as transfer learning to overcome data limitations and the use of mobile and drone-based platforms for field inspections. Challenges remain, including model generalization and computational demands. This paper concludes with future directions for enhancing real-time crack analysis through unsupervised learning, multi-modal data, and edge AI solutions, underscoring deep learning's transformative potential for infrastructure safety and maintenance.

Keywords: Surface Cracks; Crack Detection; Deep Learning; Civil Engineering.

Introduction

Concrete surface cracks are critical indicators of structural integrity in civil engineering, signaling potential issues that could compromise the stability and safety of essential infrastructure, including bridges, buildings, highways, and dams. These cracks often arise from environmental stressors, heavy loads, and material degradation over time, making routine inspection and early detection vital to prolonging the life and safety of concrete structures. Traditionally, assessing concrete surface cracks relies on manual visual inspection or basic imaging techniques, which are both labor-intensive and subject to human error. These methods demand trained professionals, and results can vary based on individual judgment, which leads to inconsistencies, especially in large-scale projects requiring continuous monitoring. Furthermore, manual inspections can be time-consuming and costly, and traditional imaging approaches like edge detection and thresholding are sensitive to noise, lighting variations, and surface textures, leading to inconsistent results. These limitations underscore the pressing need for more reliable, scalable, and automated solutions in concrete crack analysis. [1,2]

Artificial Intelligence (AI) and machine learning have introduced transformative advancements across various industries, including medicine [3-6], financial marketing [7-9], and infrastructure management [10,11], by enabling efficient, accurate, and automated analysis. AI, particularly through deep learning, has demonstrated impressive capabilities in image classification [12-14], object detection [15,16], and segmentation [17,18]. By automatically extracting complex patterns from vast datasets, deep learning models have minimized the need for manual feature engineering, which is essential in data-rich fields. Convolutional Neural Networks (CNNs), a form of deep learning, are particularly well-suited for processing and learning from image data, as they are capable of recognizing intricate visual patterns. This has enabled applications in diverse fields, such as medical imaging, where AI aids in identifying subtle anomalies, or autonomous driving, where AI-powered systems accurately detect and classify objects on the road.

Some researchers have applied modeling methods to analyze data in various civil engineering applications, aiming to enhance material resilience, structural safety, and sustainable practices. These data-driven approaches allow engineers to assess durability, optimize performance, and predict structural behavior under environmental and mechanical stressors [19-24]. Additionally, advanced mathematical techniques, including machine learning, are increasingly applied to critical fields within construction, particularly in concrete surface crack analysis, where they offer cuttingedge solutions for monitoring and maintaining structural health. Advanced machine learning methods such as deep learning models are proving to be groundbreaking technology in automating the detection of concrete surface cracks, providing several advantages over traditional methods [25]. By analyzing pixel-level data, CNNs can detect surface cracks with high accuracy, even in challenging conditions, such as variable lighting or surface irregularities. Deep learning models offer the ability to learn from raw image data, allowing them to detect patterns that may not be visible to the human eye or are easily detectable by conventional methods. Additionally, these models exhibit strong scalability and generalization capabilities, meaning that once trained on a representative dataset, they can be applied to other structures with similar characteristics, minimizing the need for extensive retraining. This versatility and precision make deep learning a promising tool for the future of infrastructure monitoring, enabling more efficient, accurate, and timely detection of structural flaws in concrete. Through AI-powered automation, the industry can shift from reactive to proactive maintenance, enhancing safety while reducing costs and time associated with traditional inspection methods.

State-of-the-art Techniques

The application of deep learning in the analysis of concrete surface cracks has gained significant traction in recent years due to its ability to automate and improve the accuracy of detection and analysis [26]. Deep learning models, particularly convolutional neural networks (CNNs), have been widely adopted in the field for their capacity to process and learn from large amounts of image data. In this section, we review the most notable techniques and methodologies employed in the detection, segmentation, and quantification of cracks on concrete surfaces. The focus is on various deep learning architectures and their performance in addressing the unique challenges posed by concrete structures.

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Image-Based Crack Detection

One of the most common applications of deep learning in concrete surface analysis is the detection of cracks in images [27-30]. Crack detection is fundamentally a classification problem, where each part of an image is classified as either containing a crack or being crack-free. CNNs, with their ability to automatically extract features from images, have proven to be highly effective in this task. Various architectures of CNNs have been applied, ranging from simple networks to more advanced deep architectures such as VGG, ResNet, and DenseNet. These CNN-based models have significantly outperformed traditional image processing techniques in crack detection tasks, primarily because they can automatically learn relevant features without the need for manual intervention. However, the success of these models is heavily dependent on the availability of large, well-labeled datasets, which can be a limiting factor in real-world applications.

Segmentation Approaches

Beyond simple crack detection, deep learning has made significant strides in segmenting cracks from images, providing more detailed information about the location, size, and shape of the cracks [31-34]. Segmentation is a more challenging problem compared to detection, as it requires pixel-level classification, where every pixel in an image is labeled as either belonging to a crack or not. This is crucial for a detailed analysis of the cracks' morphology, which can inform maintenance and repair strategies. One of the most widely used models for crack segmentation is U-Net, a fully convolutional network originally developed for biomedical image segmentation. U-Net is particularly effective because it employs a symmetric encoder-decoder architecture, which allows it to capture both the context and the precise localization of cracks. It also uses skip connections to retain fine-grained details, making it ideal for segmenting thin, irregular cracks in concrete surfaces. Another popular model for segmenting large, continuous cracks while still being able to capture smaller details. By preserving high-level context and fine details simultaneously, DeepLab has shown strong performance in segmenting cracks from images of varying resolutions and conditions.

Object Detection Methods

In addition to segmentation, deep learning models have been applied to crack object detection tasks, where cracks are treated as objects to be detected within larger images [35-37]. Models such as Faster R-CNN and YOLO (You Only Look Once) have been successfully used to detect cracks as objects, providing a bounding box around each detected crack. These methods are particularly useful in large-scale inspections where images of entire structures need to be analyzed quickly, as they offer a good balance between speed and accuracy. Faster R-CNN is an advanced object detection model that uses region proposal networks (RPNs) to identify candidate regions that are likely to contain cracks. This reduces the computational load by narrowing down the areas that need to be analyzed in detail. Faster R-CNN has been widely adopted in crack detection systems due to its high accuracy and ability to work in real-time applications. YOLO is also another object detection model known for its speed. Unlike region-based models, YOLO processes the entire image in one go, making it extremely fast.

Transfer Learning

One of the major challenges in applying deep learning to concrete crack analysis is the requirement for large amounts of labeled data to train effective models. Concrete structures exhibit a wide range of surface characteristics due to differences in material composition, environmental conditions, and exposure to wear and tear, making it difficult to create a comprehensive dataset that covers all possible variations of cracks. Furthermore, manually labeling such datasets is time-consuming and labor-intensive. To address these issues, researchers have turned to transfer learning, a powerful technique that allows models to leverage knowledge learned from one task and apply it to another. In the case of concrete crack detection, transfer learning significantly reduces the need for extensive labeled datasets while still achieving high performance in detection, segmentation, and analysis tasks.

Transfer learning involves taking a deep learning model that has already been trained on a large, general dataset-such as ImageNet, which contains millions of labeled images across thousands of categories-and fine-tuning it on a smaller, task-specific dataset. The key idea is that the lower layers of deep learning models learn generic features, such as edges, textures, and shapes, that are common across a wide variety of images. These learned features can be reused for new tasks with only minor adjustments to the model's higher layers, which are more specific to the task at hand. In the context of concrete crack detection, this means that a model pre-trained on general image classification tasks can be fine-tuned to detect cracks, even if the available dataset of crack images is relatively small. Transfer learning is particularly effective in fields like civil engineering, where the availability of labeled datasets is limited. Creating large datasets for concrete crack detection involves collecting images from diverse structures, labeling the cracks, and ensuring that the dataset represents a wide range of crack types, surface textures, and environmental conditions. This process is costly and time-intensive, and often results in datasets that are too small to train deep learning models from scratch without overfitting. Transfer learning addresses these challenges by enabling models to start with a strong foundation of general image features, which are then refined to recognize the specific patterns associated with cracks in concrete. Pre-trained models such as VGG, ResNet, and Inception have been commonly used as the starting point for transfer learning in crack detection. These models, pre-trained on large datasets like ImageNet, have already learned to identify basic image features that are transferable to new tasks. By fine-tuning these models on a smaller dataset of concrete crack images, researchers can achieve high accuracy in detecting and segmenting cracks without the need for an extensive labeled dataset.

Applications of Transfer Learning in Crack Detection and Segmentation

In recent studies, transfer learning has been applied to various tasks within the domain of concrete crack detection. For example, pre-trained CNN models have been used for binary classification, where an image is classified as either containing a crack or being crack-free. In such cases, only the final layers of the model need to be fine-tuned, as the earlier layers, which extract low-level features such as edges and textures, are already well-suited for crack detection. This approach not only accelerates the training process but also improves the generalization ability of the model, allowing it to perform well on new images that it has not seen before. Transfer learning has also been applied to crack segmentation, where the task is to identify the exact boundaries of cracks in images. In this case, models such as U-Net and DeepLab [38], which are designed for segmentation tasks, can be

pre-trained on large, general datasets and then fine-tuned on a smaller set of crack images. By transferring the knowledge learned from general image segmentation tasks, these models can achieve high accuracy in segmenting cracks, even when the available data is limited.

Challenges and Limitations of Transfer Learning

Despite its advantages, transfer learning is not without its challenges. One of the primary limitations is the potential mismatch between the pre-trained model's original task and the target task. For example, a model pre-trained on natural images like those in the ImageNet dataset may not always transfer perfectly to tasks involving concrete crack detection, as the visual features of cracks may differ significantly from those in natural scenes. In such cases, extensive fine-tuning may be required to adapt the model to the new domain. Another challenge is that transfer learning can sometimes lead to overfitting when the target dataset is too small. If the model is overfitted to the fine-tuning dataset, its performance on unseen data may degrade. To mitigate this risk, techniques such as data augmentation, regularization, and early stopping are often employed.

Crack Width Estimation and Quantification

In addition to detecting and segmenting cracks, estimating the width and quantifying the severity of cracks on concrete surfaces is a critical task for structural health monitoring [39,40]. The width of a crack is an essential indicator of the potential danger it poses to the integrity of a structure, as wider cracks are generally associated with more severe damage and a higher likelihood of structural failure. Traditionally, crack width measurement has been carried out manually or with the aid of image processing techniques, but these methods often lack the precision and scalability needed for large infrastructure projects. Deep learning, with its ability to analyze pixel-level data, offers a promising solution for automating crack width estimation and improving the accuracy of quantification. This section discusses the various approaches to using deep learning for crack width estimation and quantification, along with the challenges and advancements in this area.

Importance of Crack Width Estimation

Crack width estimation plays a crucial role in assessing the health of concrete structures. Not all cracks pose an immediate threat, but those that exceed certain width thresholds often require urgent attention. For example, surface cracks in bridges or tunnels that exceed a width of 0.3 mm are generally considered critical and need to be repaired to prevent further degradation. Therefore, accurately estimating the width of cracks allows engineers to prioritize repairs and allocate resources more effectively. Moreover, crack width estimation is necessary for monitoring the progression of damage over time. By comparing crack width measurements at different intervals, engineers can assess the rate of structural deterioration and predict future risks.

Deep Learning for Crack Width Estimation

Deep learning models, particularly convolutional neural networks (CNNs), have been successfully applied to the task of crack width estimation. These models can be trained to not only detect cracks but also estimate their width by analyzing the pixel intensity, contrast, and surrounding features of the crack in images. Unlike traditional methods, which rely on manually selected features or

threshold-based approaches, deep learning models can learn to estimate crack width directly from the data, making them more adaptable to different conditions and types of cracks.

- **Regression-Based Approaches**: One of the primary methods for crack width estimation using deep learning involves treating the problem as a regression task. In this approach, a CNN is trained to predict the actual width of the crack in terms of millimeters or pixels, based on input images. These regression-based models can provide continuous output, allowing for fine-grained width estimates. Studies have shown that CNNs, when properly trained, can achieve highly accurate crack width predictions, often surpassing traditional image processing methods.
- Segmentation Combined with Width Estimation: Another common approach involves combining crack segmentation with width estimation. First, a segmentation model, such as U-Net or Mask R-CNN, is used to identify the pixels corresponding to the crack. Then, post-processing techniques are applied to measure the distance between the crack edges, thereby estimating the crack's width. This two-step approach has proven effective in providing detailed information about the crack's morphology, including width, length, and continuity. By segmenting the crack at the pixel level, these models ensure a high degree of accuracy in width estimation, even for narrow or irregularly shaped cracks.
- Crack Width Quantification Using Deep Regression Networks: Some research has explored the use of deep regression networks specifically designed for quantifying crack width. These models are trained to output a numerical value representing the width of the crack based on features learned from a large dataset of labeled crack images. By focusing on the regression aspect of the problem, these networks can generate highly accurate and scalable width measurements for a wide range of crack types and sizes.

Challenges in Crack Width Estimation

Despite the success of deep learning models in crack width estimation, several challenges remain. One of the primary challenges is the variation in lighting and texture across different images. Cracks that are photographed in poor lighting or on textured surfaces can be difficult to distinguish, leading to errors in width estimation. While data augmentation techniques, such as changing the lighting conditions in training images, can help mitigate this problem, more advanced models that can robustly handle varying conditions are still needed. Another challenge is the resolution of the input images. Accurate crack width estimation requires high-resolution images, particularly for very narrow cracks. Low-resolution images may not capture the fine details needed for precise width measurement. To address this, some researchers have explored the use of super-resolution techniques in conjunction with deep learning models to enhance the quality of input images before estimating crack width. Moreover, cracks in concrete surfaces often exhibit irregular shapes and jagged edges, which can make it difficult for models to accurately estimate their width. Unlike smooth, well-defined cracks, these irregular cracks require models that can adapt to non-linear geometries. Advances in model architectures, such as deformable convolutional networks, have shown promise in addressing this issue by allowing the network to adjust its convolutional kernels to better capture the shape of irregular cracks.

Qualification of Crack Severity

In addition to estimating crack width, it is important to quantify the overall severity of cracks in terms of structural health. Crack severity quantification involves assessing not only the width but also the length, depth, and pattern of cracks, which can provide a more comprehensive understanding of the damage. Deep learning models can be extended to incorporate these additional factors, enabling more accurate assessments of structural health. For example, deep learning models that combine crack width estimation with length measurement and pattern recognition can provide detailed reports on the extent of damage. These models can automatically classify cracks based on their severity, helping engineers prioritize which areas require immediate attention. In some cases, models are also trained to recognize crack propagation patterns, which can be used to predict future crack growth and potential structural failures.

Practical Applications of Crack Width Estimation

Deep learning models for crack width estimation have been deployed in a variety of real-world applications. For instance, mobile apps and drone-based inspection systems are increasingly incorporating crack width estimation algorithms to provide on-site assessments of concrete structures. These systems can capture images of concrete surfaces and, using pre-trained deep learning models, instantly estimate the width and severity of any detected cracks. This enables real-time decision-making and reduces the need for manual inspection. Additionally, crack width estimation models have been integrated into structural health monitoring systems for bridges, tunnels, and dams. These systems continuously monitor key areas of the structure, providing ongoing updates on crack width and severity. By automating the crack measurement process, these systems help engineers detect potential problems early, allowing for preventative maintenance and reducing the risk of catastrophic failure.

Future Directions in Crack Width Estimation and Quantification

As deep learning techniques continue to evolve, future research is likely to focus on improving the accuracy and robustness of crack width estimation models, particularly in challenging real-world conditions. The integration of 3D imaging and LiDAR data with deep learning models may provide more detailed information on crack depth and orientation, enabling more comprehensive assessments of structural damage. Moreover, advances in self-supervised learning and active learning may reduce the need for large, labeled datasets, allowing models to be trained on unlabeled or partially labeled crack images. This would make it easier to deploy crack width estimation models in a wider range of settings, including remote or difficult-to-access structures.

Real-Time Monitoring and Mobile Applications

As infrastructure ages, the need for efficient and timely monitoring of concrete structures becomes more critical. Traditional methods of crack detection, which rely on manual inspections or periodic monitoring, are often not sufficient to catch early signs of structural failure, particularly in largescale or remote structures such as bridges, tunnels, or dams. Deep learning has enabled the development of real-time monitoring systems that provide continuous analysis of concrete surfaces, helping to detect cracks early and alert engineers to potential issues before they escalate. Moreover, the integration of mobile applications and drone-based platforms equipped with deep learning models has significantly expanded the accessibility and ease of concrete crack detection. This section explores the various real-time monitoring systems and mobile applications that use deep learning to detect, segment, and quantify cracks on concrete surfaces.

Real-Time Monitoring Systems

Real-time structural health monitoring (SHM) systems leverage sensors, cameras, and deep learning algorithms to provide ongoing assessments of critical infrastructure [41,42]. These systems are designed to operate continuously, automatically analyzing images of concrete surfaces and alerting engineers if cracks are detected or if existing cracks worsen. The key advantage of real-time monitoring systems is their ability to provide early warnings, allowing maintenance teams to take preventive action before minor cracks develop into serious structural defects. One of the most effective implementations of real-time monitoring uses fixed camera systems installed in key areas of a structure. These cameras capture images or video streams of the concrete surface at regular intervals, which are then processed by deep-learning models to detect cracks. CNN-based models, such as ResNet or Faster R-CNN, can detect cracks in real time by analyzing each frame, while segmentation models like U-Net or DeepLab can identify and track the progression of specific cracks over time. In addition to detecting new cracks, real-time monitoring systems can also measure changes in crack width, length, and other critical parameters. This capability is particularly important for crack progression analysis, where the goal is to understand how cracks evolve and to predict the likelihood of structural failure. By continuously monitoring these changes, real-time systems help engineers prioritize repairs based on the severity and urgency of detected cracks.

Mobile Applications for Crack Detection

The advent of mobile technology has further enhanced the practical applications of deep learning in concrete crack detection. Mobile applications equipped with deep learning models now enable onsite inspection teams to capture images of concrete surfaces and instantly analyze them for cracks. These mobile apps are particularly useful for conducting quick assessments in remote or hard-toreach locations, such as the underside of bridges or the inside of tunnels, where installing permanent monitoring systems may not be feasible. Mobile applications typically use pre-trained deep learning models, such as CNNs or segmentation networks, to process the images captured by the device's camera. By utilizing the computational power of modern smartphones, these apps can analyze highresolution images in real-time, providing immediate feedback on the presence and severity of cracks. The use of transfer learning is particularly advantageous in this context, as models pre-trained on large datasets can be fine-tuned to perform well on the smaller datasets typically available for specific infrastructure projects. Several research studies and commercial solutions have already developed mobile applications for concrete crack detection. These apps often include features such as automatic crack width estimation, real-time alerts, and the ability to store inspection records for future reference. Additionally, some apps allow engineers to annotate detected cracks manually, providing further flexibility for in-field inspections.

Drone-Based Platforms

In addition to mobile applications, drone-based platforms are increasingly being used for large-scale inspections of concrete structures. Drones, equipped with high-resolution cameras and GPS systems, are capable of capturing detailed images of hard-to-access or dangerous areas, such as the tops of high-rise buildings or the undersides of bridges. By automating the image collection process, drones significantly reduce the time and effort required for inspecting large structures, making them an ideal tool for civil engineers. Once the images are captured, they can be processed either onboard the drone (using edge AI) or transferred to a remote server for analysis. In many cases, the captured images are fed into deep learning models to detect cracks or other defects. CNNs, Faster R-CNN, YOLO (You Only Look Once), and Mask R-CNN are commonly used in drone-based crack detection platforms due to their speed and accuracy. These models can process large volumes of images quickly, making real-time crack detection feasible for large-scale infrastructure inspections. Drone platforms are especially useful in remote areas where traditional monitoring systems may not be available or where manual inspection is difficult. For example, inspecting the top of a dam or a remote bridge with manual methods could be both dangerous and time-consuming. With drones, engineers can quickly capture images of these areas and immediately analyze them for cracks or other structural issues. Moreover, the use of GPS tagging allows the location of each detected crack to be precisely mapped, enabling targeted repairs.

Benefits of Real-Time Monitoring and Mobile Applications

The integration of deep learning with real-time monitoring systems and mobile applications offers several key benefits for infrastructure management. First, these systems significantly reduce the reliance on manual inspections, which are prone to human error and often miss early-stage cracks. By automating the crack detection process, deep learning-based systems ensure more consistent and accurate results, allowing for earlier detection of potential issues. Second, real-time monitoring systems provide continuous, up-to-date information about the condition of a structure. This allows for proactive maintenance, as engineers can monitor the progression of cracks over time and schedule repairs before they become critical. This is particularly important for structures that are subject to heavy loads or extreme environmental conditions, where cracks can rapidly worsen if left unchecked. Mobile and drone-based applications also offer unparalleled flexibility and scalability. Mobile apps can be deployed quickly and inexpensively, allowing for on-the-go crack detection in almost any location. Similarly, drone platforms enable large-scale inspections of infrastructure that would be difficult or dangerous to inspect manually. Together, these technologies make it easier for civil engineers to manage infrastructure and ensure that minor issues are addressed before they escalate into major problems.

Challenges in Implementing Real-Time Systems and Mobile Applications

Despite the numerous advantages of real-time monitoring and mobile applications, several challenges remain in implementing these technologies on scale. One of the primary challenges is the processing power required to run deep learning models in real time. While modern smartphones and drones are increasingly capable of handling deep learning tasks, high-resolution images or videos can still strain the device's computational resources, leading to slower processing times or reduced accuracy. Another challenge is the variability of environmental conditions in real-world scenarios.

Changes in lighting, weather, or surface texture can significantly affect the performance of deeplearning models, particularly in outdoor environments. For example, shadows, reflections, or dirt on the concrete surface can cause false positives or negatives in crack detection. To mitigate these issues, deep learning models must be trained on diverse datasets that include a wide range of environmental conditions, and preprocessing techniques, such as contrast adjustment, must be applied to improve robustness. Moreover, the cost of deploying real-time monitoring systems on large infrastructure projects can be prohibitive. While mobile applications and drones offer affordable alternatives for smaller-scale inspections, installing fixed camera systems and ensuring reliable data transmission for real-time analysis across large structures can be expensive. This is particularly true for remote locations where access to power and data networks may be limited. Developing more cost-effective solutions, such as edge computing devices that can process data locally, may help reduce the cost of large-scale deployments.

Future Directions in Real-Time Monitoring and Mobile Applications

Looking forward to advances in edge AI and 5G technology are likely to drive further improvements in real-time monitoring and mobile applications for concrete crack detection. Edge AI, which involves running AI models on devices with limited processing power (such as drones or smartphones), could reduce the need for high-power servers and make real-time processing more accessible in remote locations. Similarly, the widespread adoption of 5G networks could facilitate faster data transmission, enabling real-time analysis even in areas with poor connectivity. Additionally, future research may focus on integrating multi-modal data—such as thermal imaging, acoustic signals, or LiDAR—with deep learning models to provide a more comprehensive assessment of structural health. By combining data from multiple sources, real-time monitoring systems could improve the accuracy of crack detection and provide deeper insights into the underlying causes of structural damage.

Challenges and Limitations

While deep learning has revolutionized concrete surface crack detection and analysis, several challenges and limitations must be addressed before these techniques can be widely adopted in realworld applications. The development of accurate and reliable crack detection systems using deep learning requires overcoming issues related to data availability, model generalization, computational resource demands, environmental variability, and the deployment of models in operational settings. In this section, we discuss these challenges in detail and explore potential solutions to mitigate their impact.

Data Availability and Quality

One of the primary challenges in applying deep learning to concrete crack detection is the lack of large, high-quality labeled datasets. Deep learning models, particularly convolutional neural networks (CNNs), require vast amounts of labeled data to train effectively. In many cases, the datasets available for crack detection are limited in size and do not cover the full range of crack types, surface textures, or environmental conditions that may be encountered in real-world applications.

- Limited Data for Crack Detection: Unlike fields such as natural image classification, where massive datasets like ImageNet are available, the domain of civil engineering has relatively few publicly accessible datasets for concrete crack detection. This limits the ability of models to generalize to different structures, surfaces, and lighting conditions. Additionally, labeling crack images for segmentation tasks is time-consuming, as it requires pixel-level annotations, further restricting the size of available datasets.
- Solution Data Augmentation and Synthetic Data: To address this challenge, researchers often rely on data augmentation techniques, such as rotation, scaling, and flipping, to artificially expand the size of the dataset. Another promising approach is the use of synthetic data generated through techniques like GANs (Generative Adversarial Networks) or simulation-based methods, which create realistic images of cracks under various conditions. By supplementing real-world datasets with synthetic images, deep learning models can be trained on a broader range of crack types and surface textures, improving their ability to generalize.

Model Generalization

Another challenge is ensuring that deep learning models generalize well to different environments and concrete surfaces. In real-world scenarios, cracks can vary significantly in appearance due to differences in lighting, camera angle, surface texture, and environmental conditions. A model trained in images from one type of concrete surface or under specific lighting conditions may perform poorly when applied to different surfaces or environments.

- Generalization Across Different Surfaces: Cracks in concrete structures can exhibit a wide variety of shapes, sizes, and textures, depending on the material composition, age, and environmental stressors. A model that performs well on one type of crack or surface may not generalize well to other types, particularly when the surface is rough, textured, or dirty. This variability can lead to false positives or negatives, reducing the reliability of the model in diverse real-world conditions.
- Solution Transfer Learning and Fine-Tuning: Transfer learning offers a potential solution to this problem. By using pre-trained models and fine-tuning them on smaller, domain-specific datasets, researchers can improve model generalization across different surfaces and environments. Additionally, domain adaptation techniques can be used to adjust the model's parameters to perform well in different contexts, even when the target domain differs from the training domain.

Environmental Variability

Environmental factors, such as lighting conditions, shadows, reflections, and surface dirt, pose significant challenges for deep learning models in crack detection. Concrete surfaces are often exposed to harsh environmental conditions, and images of these surfaces may be taken at different times of day or in varying weather conditions. As a result, cracks may be obscured or appear differently in images, making it difficult for models to accurately detect and segment them.

- **Impact of Lighting and Noise**: In outdoor environments, changes in lighting, such as shadows or glare, can significantly affect the appearance of cracks in images. Additionally, surface dirt, debris, or weather-related wear can cause visual noise, making it harder for deep learning models to distinguish cracks from other surface irregularities.
- Solution Robust Data Preprocessing and Model Adaptation: To mitigate these challenges, advanced data preprocessing techniques are often applied to normalize the images before feeding them into the deep learning models. Techniques such as contrast enhancement, histogram equalization, and noise reduction can help improve the visibility of cracks in challenging environmental conditions. Additionally, data augmentation can simulate these conditions during training, allowing the model to become more robust to changes in lighting, texture, and noise. Researchers are also exploring adaptive models that can dynamically adjust to environmental conditions, improving performance in real-time applications.

Computational Resource Demands

Deep learning models, especially those used for crack segmentation or object detection, can be computationally expensive to train and deploy. High-performance models like Mask R-CNN, U-Net, or ResNet require significant computational power, particularly when processing high-resolution images of concrete surfaces. For real-time monitoring or mobile applications, the computational resource demands may exceed the capabilities of local devices, such as smartphones or drones, making deployment challenging.

- **High Computational Requirements for Training and Inference:** Training deep learning models on large datasets requires powerful GPUs or cloud computing resources, which may not always be available in civil engineering projects. Moreover, deploying these models on resource-constrained devices, such as drones or edge computing systems, requires optimization techniques to reduce the model's memory and processing requirements without sacrificing accuracy.
- Solution Model Compression and Edge AI: One approach to address this issue is model compression, where techniques like quantization, pruning, and knowledge distillation are used to reduce the size of the model while maintaining its performance. Additionally, Edge AI—the practice of running AI algorithms on edge devices such as drones or mobile phones—can enable real-time crack detection with lower computational requirements. By optimizing models for edge deployment, engineers can use deep learning in remote or resource-constrained environments without relying on powerful centralized servers.

False Positives and Negatives

One of the key limitations of deep learning models in crack detection is the potential for false positives (incorrectly identifying non-crack regions as cracks) and false negatives (failing to detect actual cracks). This can occur when the model misinterprets surface irregularities, shadows, or dirt as cracks, or when it fails to recognize faint or subtle cracks.

- Impact of False Positives and Negatives on Decision Making: False positives can lead to unnecessary repairs and increased costs, while false negatives can result in missed cracks that may worsen over time and lead to structural failure. In critical infrastructure projects, the reliability of the model's predictions is paramount, as even minor errors in crack detection can have serious consequences.
- Solution Ensemble Models and Post-Processing: One approach to reducing false positives and negatives is to use ensemble models, where multiple deep learning models are combined to make more accurate predictions. By aggregating the predictions of several models, the system can reduce the likelihood of errors. Additionally, post-processing techniques can be applied to refine the model's predictions and eliminate false positives. For example, combining deep learning with traditional image processing methods, such as edge detection or morphological operations, can improve the accuracy of crack detection by filtering out irrelevant features.

Cost and Scalability

Implementing deep learning systems for crack detection on a large scale can be costly, particularly when factoring in the need for high-performance computing resources, data collection infrastructure, and skilled personnel to manage the system. Additionally, while deep learning models can be highly effective for specific tasks, scaling these solutions across large infrastructure projects with diverse conditions can be challenging.

- **Cost of Deployment:** Setting up real-time monitoring systems with deep learning models requires significant upfront investment in cameras, sensors, and computing hardware. In remote locations, ensuring reliable data transmission and power supply can further increase costs. Moreover, training deep learning models requires substantial computational resources, particularly when dealing with large datasets or complex models.
- Solution Solution Efficient model Deployment and Cloud-Based Solutions: To reduce costs, engineers can explore cloud-based solutions that enable remote model training and inference without the need for expensive local hardware. By processing data in the cloud, deep learning models can be deployed more efficiently across multiple locations. Furthermore, optimizing models for energy efficiency and scalability—such as by using low-power edge AI devices—can help reduce operational costs, making deep learning-based crack detection more accessible for large-scale infrastructure projects.

Conclusion

Deep learning has shown transformative potential in automating concrete crack detection, enabling accurate, efficient, and scalable monitoring of structural health. By advancing CNNs, segmentation, and object detection techniques, deep learning reduces reliance on manual inspections, delivering real-time, consistent results. Despite challenges such as data limitations, model generalization, and computational demands, future solutions like unsupervised learning, multi-modal data integration, and edge AI promise to enhance these systems. By enabling earlier interventions and efficient maintenance planning, deep learning is set to play a critical role in sustaining infrastructure safety and longevity, paving the way for widespread adoption across various infrastructure projects.

Conflict of interest

The authors declared no conflict of interest.

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